



## INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

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<p>(54) Title: FAULT DIAGNOSIS IN CPAP AND NIPPV DEVICES</p>		
<p>(57) Abstract</p> <p>A ventilation device for non-invasive positive pressure ventilation (NIPPV) or continuous positive airway pressure (CPAP) treatment of a patient has a gas flow generator (1, 2), a gas delivery circuit (5, 6) optionally including a humidifier (H), a controller (4) and sensors (10, 11, 12, 13, 14) monitoring values of operational parameters of the device. The device further includes one or more relationships stored in data storage of the controller relating combinations of parameter values as being indicative of fault conditions of the device operation, the sensors and/or the fault detection process.</p>		

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## **Fault Diagnosis in CPAP and NIPPV Devices**

### **BACKGROUND OF THE INVENTION**

This invention relates to ventilation devices such as non-invasive positive pressure  
5 ventilation (NIPPV) and continuous positive airway pressure (CPAP) devices which  
function to supply a patient with a supply of clean breathable gas (usually air, with or  
without supplemental oxygen) at a prescribed pressure or pressures at appropriate  
times during the patient's breathing cycle. The specification discloses a method and  
apparatus for fault diagnosis in such devices.

10

An example of a suitable device in which the invention may be included is the  
AutoSet® T device (ResMed Ltd., Australia), which may be used for treating sleep  
disordered breathing, such as Obstructive Sleep Apnea (OSA), as described in US  
Patent 5,704,345 (Berthon-Jones).

15

A NIPPV or CPAP device typically includes a flow generator, an air filter, a mask, an  
air delivery conduit connecting the flow generator output to the mask, various sensors  
and a microprocessor-based controller. The flow generator may include a servo-  
controlled motor and an impeller. The sensors measure, among other things, motor  
20 speed, gas volumetric flow rate and pressure. The air delivery circuit is that portion of  
the device's airflow path comprising the air inlet, the filter, the flow generator, the  
conduit and the mask. The device may optionally include a humidifier in the air  
delivery circuit. The controller may include data storage means.

25 One problem compromising the effective operation of such devices is that with time,  
the air inlet filter may become dirty, increasing the filter's resistance to the flow of air.  
It is known to provide a warning light which is activated after a given number of hours  
of operation of the device, to indicate that the filter should be cleaned or replaced.  
Such an approach does not take into account the fact that the rate of accumulation of  
30 dirt on the filter will depend on the environment in which the device is used. It may

also be found that the patient may continue to use the device despite the warning light and thereby receive inadequate therapy. Importantly, the air delivery circuit may become partly or completely blocked for other reasons, without a warning being given.

5

## SUMMARY OF THE INVENTION

At a given rotational speed of the motor, and a given air delivery circuit pneumatic impedance, the flow generator will deliver gas at a particular pressure. By measuring  
10 the resultant pressure for a range of motor speeds, for different circuit impedances, and with and without the humidifier, characteristic curves of the device may be obtained. If then the values of motor speed, flow rate and pressure are measured by transducers during operation of the device, the current pneumatic impedance may be  
15 the resistance of the air filter and thus more accurately indicate when the filter needs changing. Furthermore, partial or complete blockage of the air delivery circuit will also be capable of detection by such an arrangement.

An acceptable range of measured pressure values may be calculated for a given set of  
20 conditions, defined, for example, by upper and lower characteristic curves. The motor speed may be increased to maintain an acceptable output pressure as a response to increased impedance, while a pressure outside an acceptable range may be indicative of the need to replace the filter.

25 Such an arrangement relies on the transducers providing correct information regarding the monitored parameters, and in accordance with preferred forms of the invention the existence of transducer fault conditions is also responded to by the system.

The invention therefore broadly resides in a method or apparatus in which, in each  
30 case, acceptable and unacceptable regions for transducer values are chosen. During operation of the device, the transducer values are measured and compared with the predetermined regions. When the transducers are in unacceptable regions, corrective

action is taken, for example, by issuing a warning of the fault or shutting down the device.

Thus, in one form, the present invention provides apparatus for supplying breathable  
5 gas to a patient, including a gas flow generator, a gas delivery circuit, a controller  
having data storage means, sensors monitoring values of operational parameters of the  
apparatus, and fault detection means including at least one relationship stored in said  
data storage means, said relationship relating a combination of values of at least two  
of said parameters as indicative of a fault condition of said apparatus, said fault  
10 detection means further including means testing said at least two said monitored  
operational parameter values against said stored relationships and instigating a  
response upon detection of a fault condition.

Preferably, said monitored parameters include at least motor speed of the flow  
15 generator, gas flow rate and gas delivery circuit pneumatic pressure.

In the practice of this aspect of the invention, a device embodying the invention will  
before clinical use be subjected to a calibration routine in which the motor speed and  
air delivery circuit pneumatic pressure are varied, while measuring pressure and flow  
20 rate. From these measurements characteristic curves are determined and stored in the  
data storage means associated with the controller.

During clinical use, flow rate, pressure and speed are monitored. The appropriate  
characteristic curves and acceptable range of pressure are selected for the current set  
25 of operating conditions. The measured pressure is tested against the acceptable range,  
and if it lies outside that range, a fault is asserted. If a fault is asserted, an error  
message may be given on the output screen, an alarm given, or the machine may be  
shut down.

30 In other embodiments of the invention, all of the transducers (such as snore, flow and  
speed transducers) are tested against predetermined characteristic curves for fault  
conditions.

Further embodiments are described below in relation to CPAP apparatus, but will be understood as being applicable to any of the above described forms of ventilatory treatment or assistance.

5

#### BRIEF DESCRIPTION OF THE DRAWINGS

Figures 1(a) to (d) illustrate possible configurations of a device employing a humidifier and a loop back box.

10 Figure 2 CPAP Apparatus

Figure 3 Desirable operating region for blower (a) high speed, and (b) low speed

Figure 4 Computer software block diagram

Figure 5 Pressure transducer fault regions

Figure 6 Flowchart: Detect pressure transducer stuck low

15 Figure 7 Flowchart: Detect pressure transducer stuck high

Figure 8 Flowchart: Detect flow transducer stuck low

Figure 9 Flowchart: Detect flow transducer stuck high

Figure 10 Flowchart: Detect snore transducer stuck low

Figure 11 Flowchart: Detect snore transducer stuck high

20 Figure 12 Flowchart: Detect speed transducer stuck low

Figure 13 Flowchart: Detect speed transducer stuck high

Figure 14 Flowchart: Detect stalled motor

Figure 15 Flowchart: Detect restricted motor

Figure 16 Software fault diagnosis regions

25 Figure 17 Flowchart: Software fault diagnosis

In the figures, the "D" symbol is a logical "and", the rectangle symbol is a block of code. The triangle symbol is a comparator, if the conditions are met, then the output is a logical "1", otherwise "0".

## DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

An example of a problem solved by the present invention is provided by the  
5 Applicant's AutoSet<sup>®</sup> T device, which is provided with a "loop back" box which  
facilitates the optional connection of a humidifier into the air delivery circuit upstream  
of the pressure transducer. The arrangement is described in co-pending Australian  
patent application No. 71978/98 filed 18 June 1998 and is schematically illustrated in  
Figures 1(a) to (d) hereof.

10 Figures 1(a) and (b) show the correct manner in which the loop back box and the  
humidifier are intended to be connected. In Figure 1(a) the humidifier is not used, and  
the loop back box connects the flow generator (F) to the internal conduit where the  
pressure sensor (T) is located. The mask (M) is connected to its outlet downstream of  
15 the pressure sensor.

Typically the ventilatory assistance for CPAP or NIPPV treatment is delivered to the  
patient by way of nasal mask. Alternatively, a mouth mask, a full face mask or nasal  
prongs can be used. In this specification, any reference to a mask is to be understood  
20 as incorporating a reference to a nasal mask, mouth mask, full face mask or nasal  
prongs.

In Figure 1(b) the humidifier (H) replaces the loop back box and gas correctly flows  
from the flow generator, through the humidifier, past the pressure transducer and thus  
25 to the mask.

In order that the AutoSet<sup>®</sup> device be compatible with a large range of standard tubing,  
humidifiers and masks, the outlets all have the same size and shape. It is therefore  
possible to assemble the equipment incorrectly, as shown in Figures 1(c) and (d). In  
30 Figure 1(c) neither the loop back box nor the humidifier is used, and the mask is  
attached directly to the outlet of the flow generator, thus by-passing the pressure  
sensor. In Figure 1(d) the mask receives no pressurised air. In either of these situations

the pressure transducer will give an incorrect indication of mask pressure and this may lead to a dangerous overpressure in an automatically adjusting device.

By monitoring the pressure transducer output in conjunction with motor speed this  
5 dangerous condition can be detected and responded to. Boundary conditions of high motor speed and low pressure, and low motor speed and high pressure, may be chosen as indicators of a fault condition. The same conditions can also be used to assert a fault in the case of a defective pressure transducer, and are described later in relation to Figures 6 and 7.

10

A similar approach enables a stalled motor condition to be catered for in the NIPPV device without the use of devices such as fuses. A stalled motor will not generate any pressure, and the feedback control loop to the servo unit will cause an increase in motor current. Conventionally, a fuse or other cut-out device will be required to  
15 protect the motor from overheating. If however, the motor parameters of motor speed and a motor drive parameter such as a function derived from current are monitored, a fault condition may be established. For example, if the motor parameter is greater than 80% and the motor speed remains below 4,500 rpm for 0.2 seconds, a "Stalled Motor" condition exists. A "Restricted Motor" condition can also be defined, for example  
20 where the motor parameter exceeds 95% and the motor speed is lower than 15,000 rpm, for at least 30 seconds.

The corrective action in these cases is to disable the motor and otherwise disable operation of the machine until service can be performed, this mode being termed the  
25 "service required" mode.

Malfunction of the motor speed transducer will impact on the detection of motor stall, and on other fault detection functions which will be described below. In this specification there is therefore also described the manner in which the invention may  
30 be applied to the detection of motor speed transducer failure.



It will be seen that the invention can be put into effect with appropriate software, using the control electronics already provided in the machine, and therefore represents an economical solution to the diagnostic objectives.

5 *Advantages of the invention*

- The invention has a number of advantages over the prior art. Firstly, safety can be improved. The greatest proportion of CPAP treatment apparatus are for use in a non-clinical setting, in which environment a user is untrained to detect conditions indicative of faults. Such fault conditions can lead to the CPAP treatment apparatus
- 10 being ineffective or even dangerous. For example, the flow generators used in certain modern CPAP treatment apparatus are capable of delivering pressures in excess of 30 cm H<sub>2</sub>O, which may be required in certain situations, but excessive and potentially dangerous in others.
- 15 The costs, both direct and associated, of CPAP treatment apparatus which include the invention can be reduced. Certain hardware such as fuses and other analogue circuitry may no longer be required. Furthermore, it becomes cheaper for technicians to diagnose faults since the device may be interrogated by interfacing with the controller, reducing the need to remove casing during service. Interfacing may be done locally or
- 20 remotely, for example through a network. In a clinical setting, this may have the further advantage of reducing patient disturbance.

- In the CPAP treatment device with fault diagnosis, useability is improved. It becomes possible to provide fault diagnosis and rectification information to those without
- 25 clinical or technical skills.

- The invention may also be used to predict more accurately when faults may occur, for example, to predict when a flow generator air inlet filter may need changing, based on measurements of the motor load.
- 30

In the specification, any reference to "operating parameters" is to be understood to relate to any form of data or state signal, transducer or actuator, and the mechanical

and electrical functions of component elements/apparatus of a CPAP apparatus. Any reference to "process" is to be understood to mean a unit of hardware and/or software which can perform a task or set of related tasks, for example, a fault detection process, a feedback control process, a pressure measurement process or a flow measurement process.

Following the diagnosis of a current or potential fault occurring, the response may be one or more of the following: issuing a warning of the fault condition, recording a diary entry describing the fault condition, adjusting operating parameters and switching between the functional and stand-by or stop modes, or switching the device to a service-required mode. The response may be immediate, or at some later period, for example, the morning following the sleep period during which the device was used.

Figure 2 shows a simplified schematic of a typical CPAP treatment apparatus. An impeller (1) is powered by an electric motor (2) using a servo (3) under the direction of a microprocessor-based controller (4). The supply of breathable gas is carried to the mask (5) through a flexible conduit (6). The apparatus has various switches (7), displays (8) and a number of transducers. The transducers monitor a number of processes, for example: volumetric flow rate (10) (at a predetermined point in the flow path), pressure (11) (at a predetermined point downstream of the flow generator outlet or at the mask), snore (12), flow generator rotational speed (13) and motor parameter (14).

*The concept of an acceptable region: hardware operation*

There may be a relationship between the measured blower flow rate,  $f$ , and the measured blower output pressure,  $p$ , such that  $f$  decreases when  $p$  increases. It may be desired that for acceptable operation of the device, the parameter values be kept in a certain region. The function  $R$  for that process may be written:

$$R = R(f, p)$$

Distinct functions may be determined for different conditions, for example, high and low motor speeds, as shown in Figures 3a and 3b. Alternately, the acceptable region could be defined by a 3-parameter model,  $R = R(f, p, \omega)$ , where  $\omega$  is motor speed.

#### 5 *Example of a logical test*

In a simple case, the acceptable region may be a rectangle, defined by two values of flow  $f_1$  and  $f_2$  and two values of pressure,  $p_1$  and  $p_2$ . If the estimates of the parameter values were  $\{f, p\}$  then the test to diagnose a current fault may be, for example:

- 10 If  $p > p_1$  and  $p < p_2$  and  $f > f_1$  and  $f < f_2$  then the current operation region lies within the acceptable range.

Alternatively, the method may diagnose a fault if  $\{f, p\}$  lay outside the acceptable range for an instant, or lay outside the desirable range for some duration.

15

#### *Computer software block diagram*

- Advantageously, the invention is implemented in software. In this case, no additional hardware is needed. The fault detection software processes may be executed in conjunction with existing software. This is shown in Figure 4. The inputs to the
- 20 controller (4) are analogue electronic signals indicative of the value of various sensors, transducers and other electronic circuitry. These are converted to digital signals. The hardware parameter values (41) are passed to one or both of the normal computer software processes (44) (for example, feedback control processes) and the fault diagnosis processes (43). Further parameters may be generated (42) (for
- 25 example, flags) indicative of the operation of each of the software processes, and passed back into one or both of the software processes. In addition, the processes may generate hardware instructions (45) (for example, information to be displayed, or directions to shut down the operation of the CPAP device) which are converted to analogue electronic signals and passed to the relevant hardware.

30

Fault diagnosis of each apparatus process may be executed as a distinct software process, or several apparatus processes may be monitored within a single software process.

## 5 PREFERRED MODE OF OPERATION

### *Processes monitored*

In the preferred mode of carrying out the invention, in each device, a plurality of processes are monitored. These include:

Pressure transducer operation

10 Flow transducer operation

Snore transducer operation

Speed transducer operation

Motor operation

Breath and Apnea detection algorithms

15 Fault diagnosis process operation

Air filter operation

Correct assembly of air delivery circuit

20 Modes of fault diagnosis for these processes are described in the following sections.

### *Pressure transducer*

The invention may be used to detect whether the pressure transducers are correctly operating. A consequence of a failure of a pressure transducer (11) could be  
25 overpressure or under-pressure to the mask and thus the patient. To detect such a failure condition, the transducer pressure is monitored (11) together with motor speed (13). The regions of faulty device operation are shown in Figure 5. Logical flowcharts indicating the decision process are shown in Figures 6 and 7.

30 If the sensed pressure remains below 2.0 cm H<sub>2</sub>O (62) while the motor speed is above 12,000 rpm (61) for at least 0.3 seconds (65), a fault condition is signalled as a

"Pressure Transducer Low" failure (66). If neither condition is satisfied, a timer is reset (64).

5 In a similar way, if the pressure value remains above 15 cm H<sub>2</sub>O (72) while the motor speed is below 4,500 rpm (71) for at least 0.3 seconds (75), that corresponds to a "Pressure Transducer High" failure (76). On detection of either form of pressure transducer failure, corrective action is taken to disable power to the motor (2) and a notification is given on a display. The user may then check all components in the air delivery circuit for an obstruction or an incorrect connection.

10

An additional embodiment is used for the pressure transducer fault diagnosis mode in conjunction with motor speed. The output from the pressure transducer is split into two signals. One signal,  $P_{\text{high}}$  remains unfiltered, whilst the other signal is low-pass filtered to become  $P_{\text{low}}$ . Each signal is tested to yield an output of "Pressure  
15 Transducer High", "Pressure Transducer Low" or "ok". The conditions for "high" and "low" are as described above. A signal which is neither high nor low is deemed to be ok. Unless the test result for both signals is "ok", a fault condition will be signalled. If the test result for both signals is "low", the fault condition is taken as an indication that the hoses are not connected.

20

#### *Flow Transducer*

A failure of the flow transducer (10) can cause errors in flow measurement, mask pressure measurement and signal processing (such as inspiratory flow flattening index, as taught in US Patent No. 5,704,345). This in turn may result in errors in the  
25 delivery pressure from the flow generator (1), compromising the efficacy of treatment. Logical flowcharts indicating the decision process are shown in Figures 8 and 9.

To detect such a fault, the flow transducer (10) signal is monitored together with motor speed (13). If the flow remains below 5 % full scale deflection (f.s.d.)(82) while  
30 the motor speed is less than 4,800 rpm (81) for more than five seconds (85), the fault condition is signalled as "Flow Transducer Low" failure (86). If neither condition is satisfied the counter is reset (84). In a similar manner, if the flow generator flow

remains above 95% f.s.d. (92) with the motor speed less than 4,800 rpm (91) for more than 5.0 seconds (95), the fault of "Flow Transducer High" is signalled (96).

- On occurrence of either fault condition, the patient is notified on a display, and in  
5 addition, the mask pressure will be increased over some time, for example, five minutes, to a predetermined level, in this case, the 95% centile of the previous session. However if that pressure value would be invalid by representing a dangerous overpressure, the pressure will be limited to 10 cm H<sub>2</sub>O.

10 *Snore Transducer*

- A failure of the snore index transducer can cause errors in the snore measurement and the calculated snore index. Such errors result in consequential errors in the treatment pressure delivered by the flow generator (1), again possibly compromising the efficacy of treatment. Logical flowcharts indicating the decision process are shown in  
15 Figures 10 and 11.

- To detect a failed snore transducer the snore transducer signal (12) and motor speed (13) are sampled. If the snore index signal remains below 5% f.s.d. (102) with the motor speed greater than 11,000 rpm (101) for more than two seconds (105), a "Snore  
20 Transducer Low" failure is signalled (106). If neither condition is satisfied the counter is reset (104). If the snore transducer (12) signal remains above 95% f.s.d. (112) while the motor speed is less than 6,000 rpm (111) for more than two seconds (115) a "Snore Transducer High" failure mode occurs (116).

- 25 The corrective action that can be taken is to notify the user of the occurrence and, if the flow generator (1) is generating a pressure, attempt to increase the pressure over some time, for example 5 minutes, to a predetermined level, for example, the 95% centile of the previous session. If that pressure value is invalid by representing a dangerous overpressure, the pressure will be limited to 10 cm H<sub>2</sub>O.

*Motor Speed Transducer*

An incorrect motor speed may impact upon functions arising from the pressure transducer (11), flow transducer (10) and snore transducer (12). Logical flowcharts indicating the decision process are shown in Figures 12 and 13. Detection of a failure of the motor speed transducer (13) is achieved by monitoring the speed (13) together with the sensed pressure (11) and flow (10) and the motor drive parameter (14). If the motor speed remains below 6,000 rpm (121) while the motor drive parameter is above 15% (122) and either the pressure is above 8.0 cm H<sub>2</sub>O (123) or (125) the flow is greater than 75% f.s.d. (124), this set of conditions being true for more than one second (128), then a "Motor Speed Low" failure is signalled as occurring (129). If any of the conditions are not met, the counter is reset (127).

If the motor speed remains above 18,000 rpm (131) while the motor drive is below 5% (132) and (136) either the pressure is below 2.0 cm H<sub>2</sub>O (133) or (135) the absolute flow is less than 10 l/min (134) for more than one second (138), a "Motor Speed High" failure is signalled as occurring (139).

The corrective action that can be taken is to notify the user of the occurrence and, if the flow generator (1) is generating a pressure, attempt to increase the pressure over some time, for example 5 minutes, to a predetermined level, for example, the 95% centile of the previous session. If that pressure value is invalid by representing a dangerous overpressure, the pressure will be limited to 10 cm H<sub>2</sub>O.

*Motor*

As noted earlier, a stalled motor will not generate any pressure. Such a condition can occur if the impeller (1) is jammed, for example. The feedback control loop from the flow generator (1) to the servo unit (3) will cause an increase in the power delivered to the motor (2), the increase continuing until maximum power is supplied. A consequence can be overheating of the motor to the extent that insulation or windings

fail and the motor must be replaced. Flowcharts describing the operation for “stalled” and “restricted” motor are shown in Figures 14 and 15 respectively.

A motor failure condition is detected by monitoring the motor speed (13) and motor drive parameter. If the motor parameter is greater than 80% (142) and (143) the motor speed remains below 4,500 rpm (141) for 0.2 seconds (145), a “Stalled Motor” condition exists (146). If any of the conditions are not met, the timer is reset (144). In a similar way, if the motor parameter exceeds 95% (152) and the motor speed is lower than 15,000 rpm (151), occurring for more than 30 seconds (155), then a “Restricted Motor” condition exists (156).

The corrective action is to disable power to the motor and otherwise disable operation of the machine until a service can be performed, this mode being termed the “service-required” mode.

15

#### *Pneumatic Performance*

In another embodiment, the method may be used to check the overall pneumatic, or air delivery, performance of the apparatus. The relevant regions are shown in Figure 3, being the desired operating region  $\zeta_d$  and fault regions  $\zeta_{f1}$ ,  $\zeta_{f2}$ . The operating regions are a function of pressure ( $p$ ), flow ( $f$ ) and motor speed ( $\omega$ ). If, the operational state of the device lies in region  $\zeta_{f1}$ , there are several possible causes:

- Dirty filter
- Internal air path blockage in the CPAP apparatus
- Leak in the internal air path of the CPAP apparatus
- 25 Flow generator failure
- Faulty speed sensor
- Faulty flow sensor
- Faulty pressure sensor
- 30 Possible responses include:
- Issuing a warning advising that the filter needs changing



Switching the apparatus to service-required mode

If the operational state of the device lies in region  $\zeta_2$ , there are several possible causes:

- 5    Faulty speed sensor
- Faulty flow sensor
- Faulty pressure sensor

The response would be to switch the device to the service required mode.

10

The embodiments described earlier may be used in conjunction with the current embodiment, to distinguish which of the sensors may be faulty.

*Fault diagnosis operation*

- 15    The events “pressure transducer stuck high” and “pressure transducer stuck low” are mutually exclusive. Similarly the flow, snore and motor speed transducers have mutually exclusive conditions. In another embodiment of the invention, the fault diagnosis processes tests whether mutually exclusive conditions have been deduced and signals an error in fault diagnosis if that event occurs.

20

*Breath and Apnea detection processes*

- Figure 16 shows the operating regions for the breath and apnea detection processes. These processes detect the presence of breathing by the user and the occurrence of apneas, these two events being mutually exclusive. During normal operation of the
- 25    CPAP device, either one or the other of these events ought to be detected. In this case, these two events lie within non-intersecting regions of  $\zeta_d$  (Figure 16). If the current operating region of the device lies outside both these two regions, then some kind of error has occurred and an error is asserted. A flowchart for this fault detection process is shown in Figure 17. While the device is operating the “Breath Detection” and
- 30    “Apnea Detection” processes are monitored. The fault detection process will assert a fault when either of the following two conditions occur:

- Apnea and Breath are asserted simultaneously
- Neither Apnea nor Breath are asserted for a predetermined period.

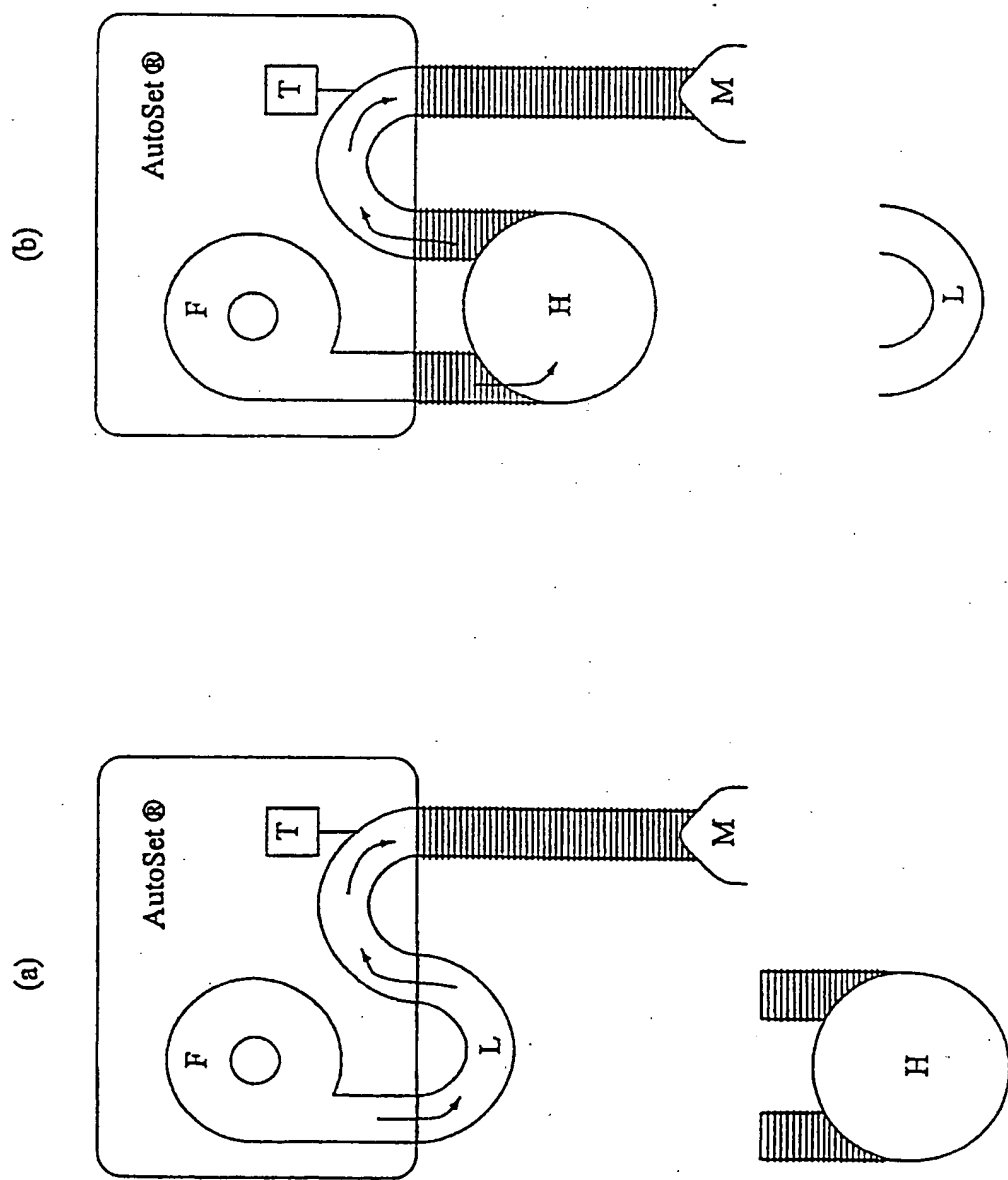
While particular embodiments of this invention have been described, it will be evident  
5 to those skilled in the art that the present invention may be embodied in other specific  
forms without departing from the essential characteristics thereof. The present  
embodiments and examples are therefore to be considered in all respects as illustrative  
and not restrictive, the scope of the invention being indicated by the appended claims  
rather than the foregoing description, and all changes which come within the meaning  
10 and range of equivalency of the claims are therefore intended to be embraced therein.

## CLAIMS

1. Apparatus for supplying breathable gas to a patient, including a gas flow generator, a gas delivery circuit, a controller having data storage means, sensors  
5 monitoring values of operational parameters of the apparatus, and fault detection means including at least one relationship stored in said data storage means, said relationship relating a combination of values of at least two of said parameters as indicative of a fault condition of said apparatus, said fault detection means further including means testing said at least two said monitored operational parameter values  
10 against said stored relationships and instigating a response upon detection of a fault condition.
2. Apparatus according to claim 1 wherein said monitored parameters include at least motor speed of the flow generator, gas flow rate and gas delivery circuit  
15 pneumatic pressure.
3. Apparatus according to claim 1 wherein the gas delivery circuit includes a gas inlet, a gas filter, the flow generator, a patient mask and a gas delivery conduit connecting the flow generator output to the mask.  
20
4. Apparatus according to claim 3 wherein the gas delivery circuit is adapted for optional addition of a humidifier.
5. Apparatus according to claim 1 wherein the apparatus is adapted to provide  
25 CPAP or NIPPV treatment to the patient.
6. Apparatus according to claim 2 wherein said stored relationship relates a combination of values of gas delivery circuit pneumatic pressure, gas flow rate and motor speed as indicative of a pneumatic impedance fault condition of said gas  
30 delivery circuit.

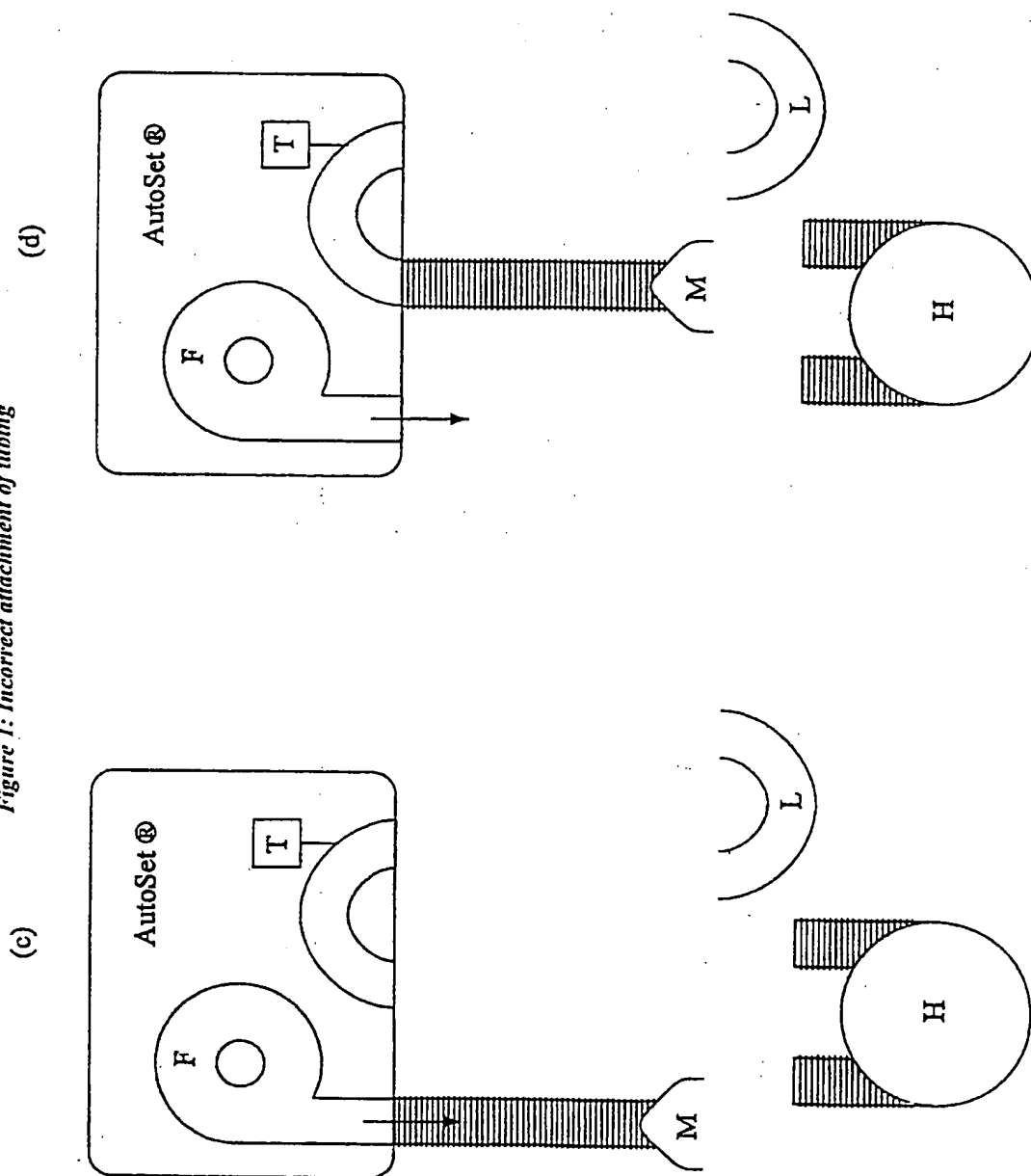
7. Apparatus according to claim 6 wherein said stored relationship includes calibration data relating pneumatic impedance against said pressure and gas flow rate at a range of motor speeds.
- 5 8. Apparatus according to claim 7 wherein said comparing means tests the combination of monitored pressure and monitored gas flow against calibration data applicable to the monitored motor speed.
9. Apparatus according to claim 2 wherein said stored relationship relates a  
10 combination of values of at least two of said parameters as indicative of a fault condition of at least one of said sensors.
10. Apparatus according to claim 9 wherein said stored relationship relates a  
15 combination of said pressure and gas flow rate as indicative of a pressure transducer fault condition.
11. Apparatus according to claim 9 wherein said stored relationship relates a  
combination of said gas flow rate and motor speed as indicative of a flow transducer  
fault condition.  
20
12. Apparatus according to claim 9 wherein said stored relationship relates a  
combination of said motor speed and output of a snore index transducer as indicative  
of a snore index transducer fault condition.
- 25 13. Apparatus according to claim 9 wherein said stored relationship relates a  
combination of said motor speed, pressure, gas flow rate and a monitored motor drive  
parameter as indicative of a motor speed transducer fault condition.
- 14.. Apparatus according to claim 13 wherein said monitored motor drive  
30 parameter is a function of motor current.

15. Apparatus according to claim 2 wherein said stored relationship relates a combination of said motor speed and a monitored motor drive parameter as indicative of a motor operation fault condition.
- 5 16. Apparatus according to claim 15 wherein said monitored motor drive parameter is a function of motor current.
- 10 17. Apparatus according to claim 1 wherein said fault detection means detects a fault diagnosis process fault condition upon simultaneous assertion of two or more mutually exclusive fault conditions.
- 15 18. Apparatus according to claim 17 wherein said fault detection means detects a breath and apnea detection process fault condition upon simultaneous assertion of both breath and apnea.
19. Apparatus according to claim 18 wherein said fault detection means further detects a breath and apnea detection process fault condition where neither breath nor apnea is asserted for a predetermined period.



**Figure 1: Correct attachment of tubing**

Figure 1: Incorrect attachment of tubing



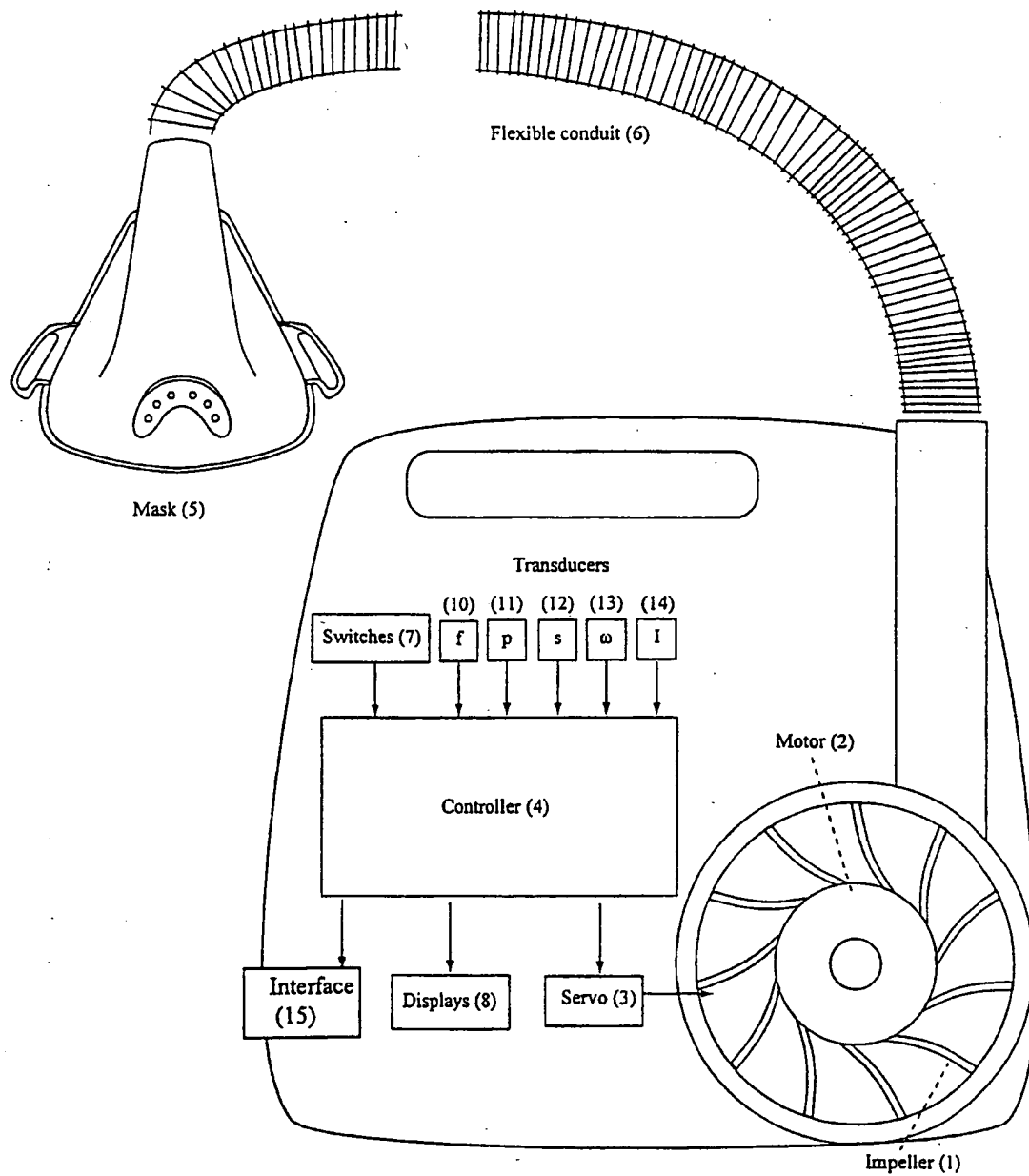


Figure 2: CPAP apparatus



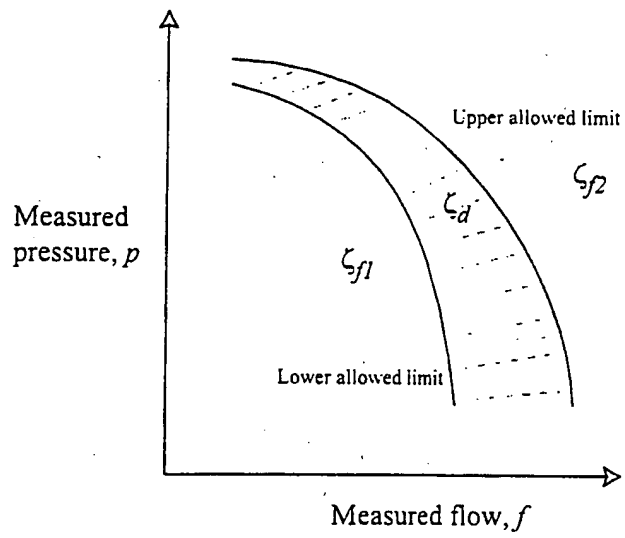


Figure 3a: High motor speed ( $\omega$ ) operation

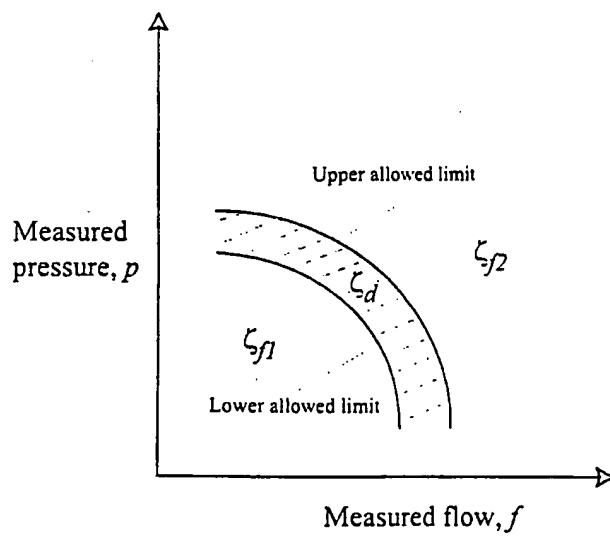


Figure 3b: Low speed motor speed ( $\omega$ ) operation

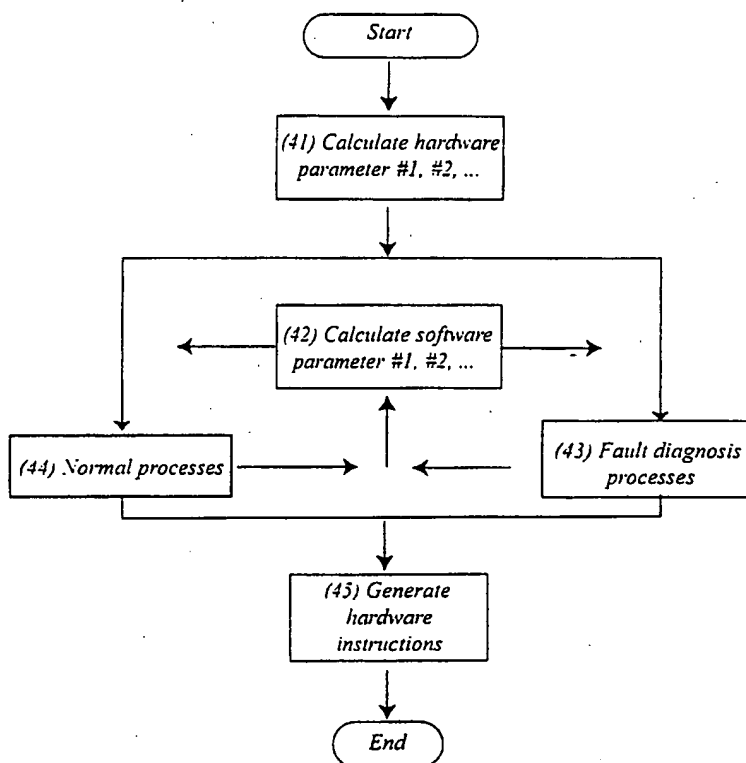


Figure 4: Fault diagnosis implemented in overall software processes

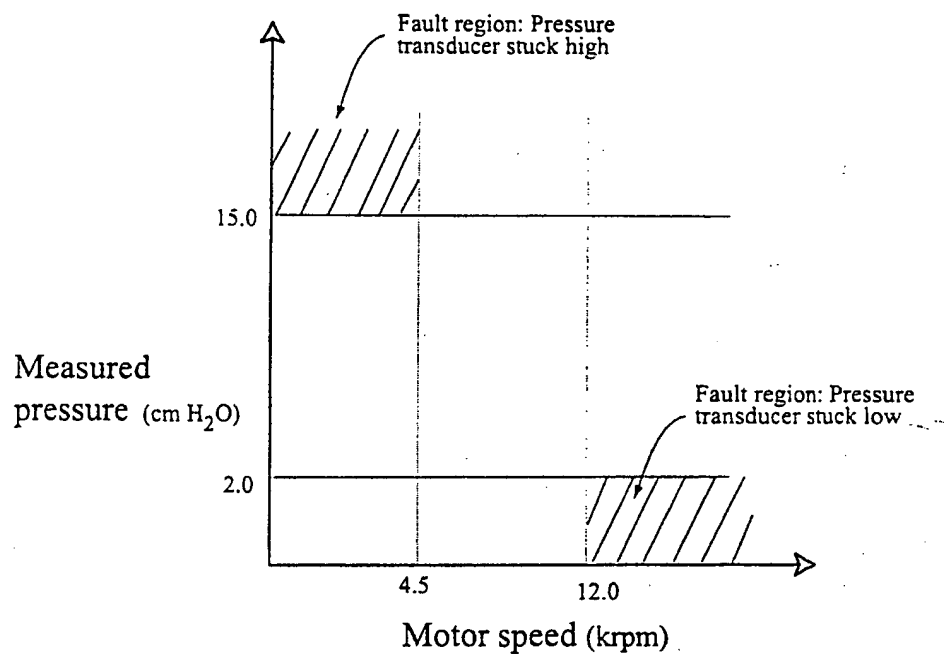


Figure 5: Pressure transducer fault regions

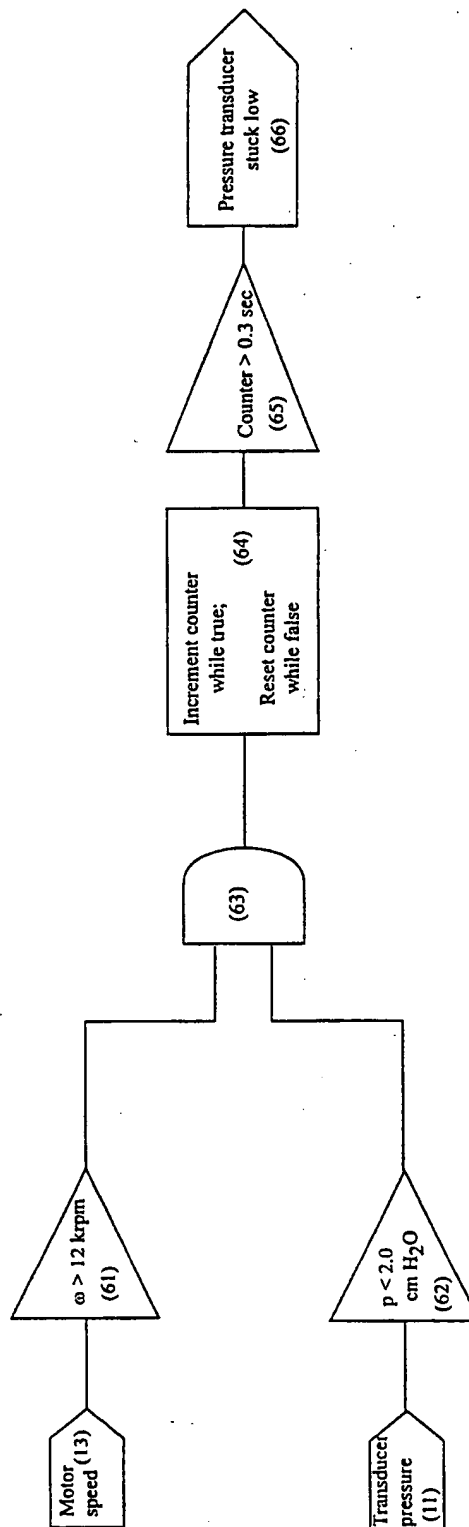


Figure 6: Detect Pressure Transducer stuck Low

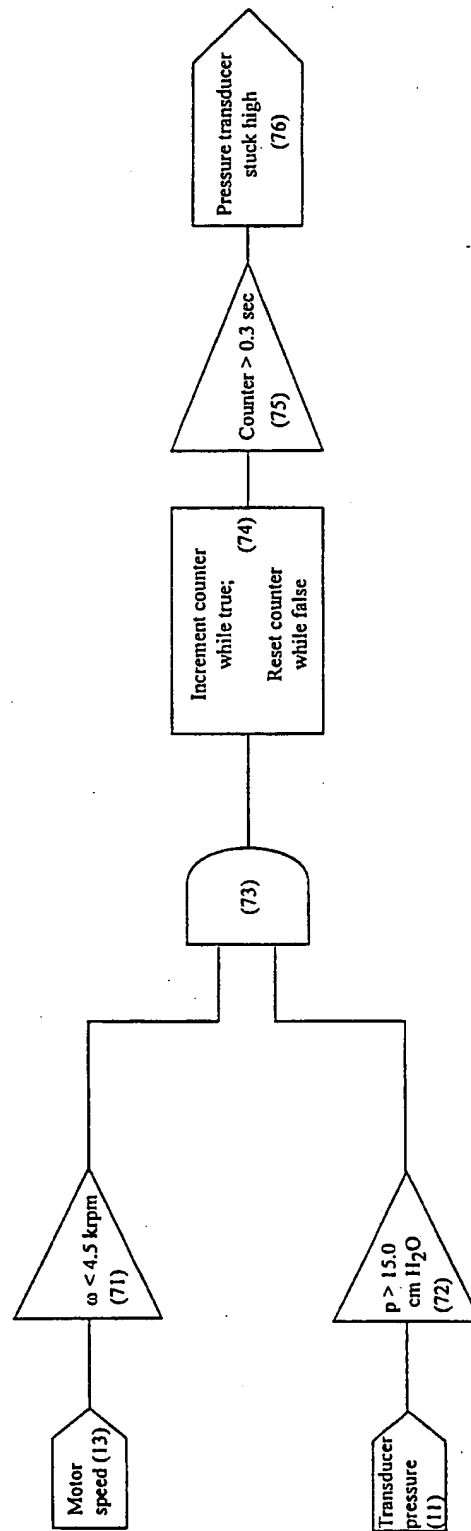


Figure 7: Detect Pressure Transducer stuck High

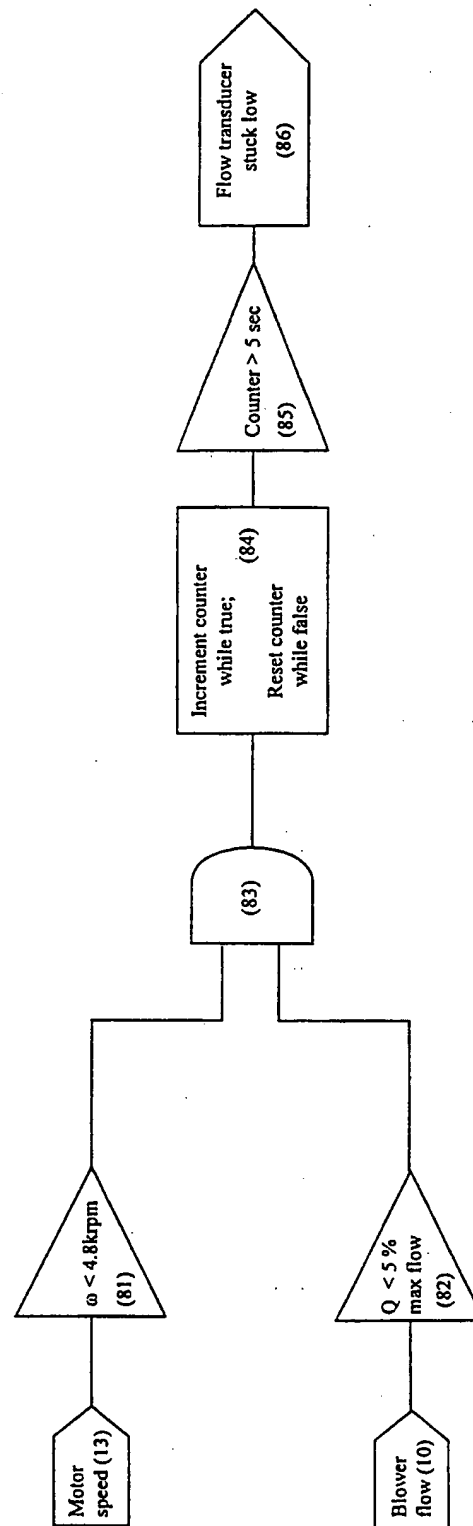


Figure 8: Detect Flow Transducer Stuck Low

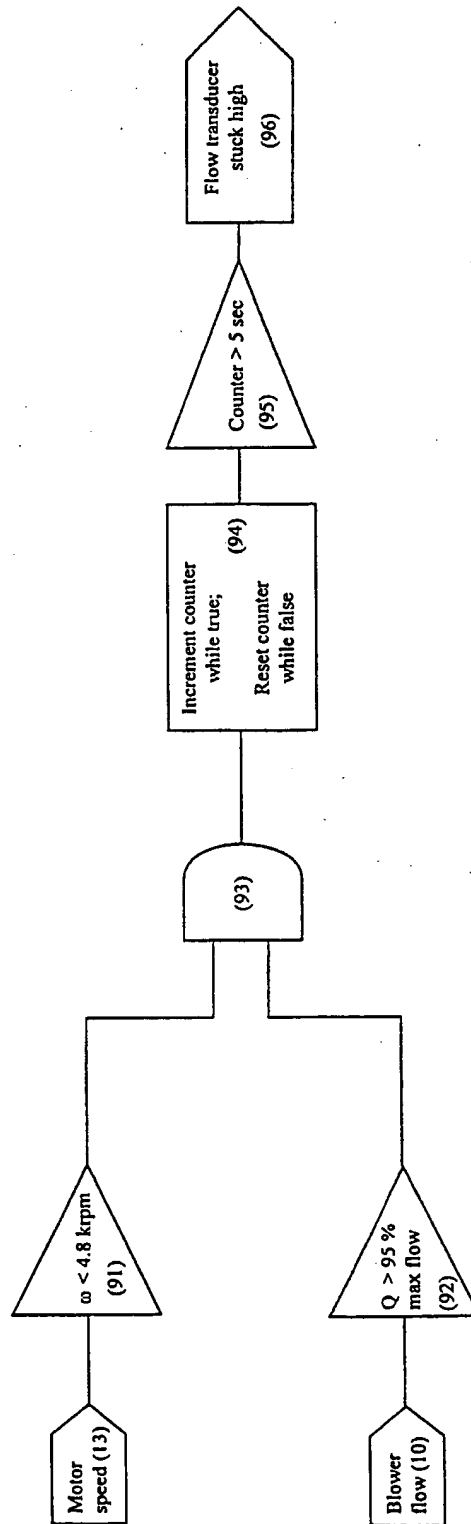


Figure 9: Detect Flow Transducer Stuck High

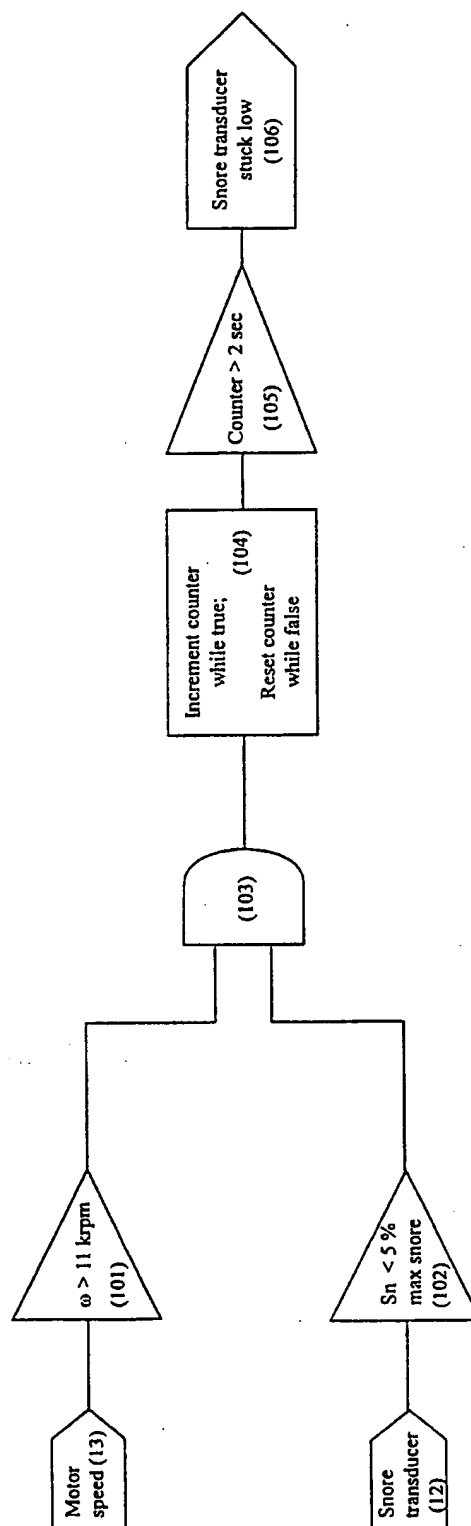


Figure 10: Detect Snore Transducer Stuck Low



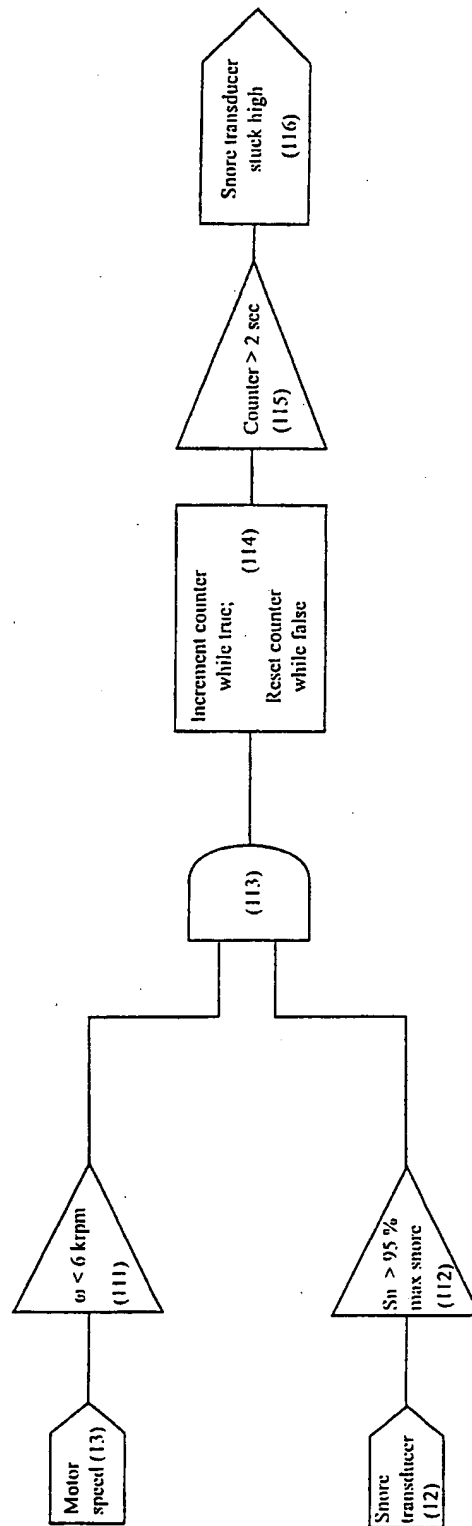


Figure 11: Detect Snore Transducer Stuck High

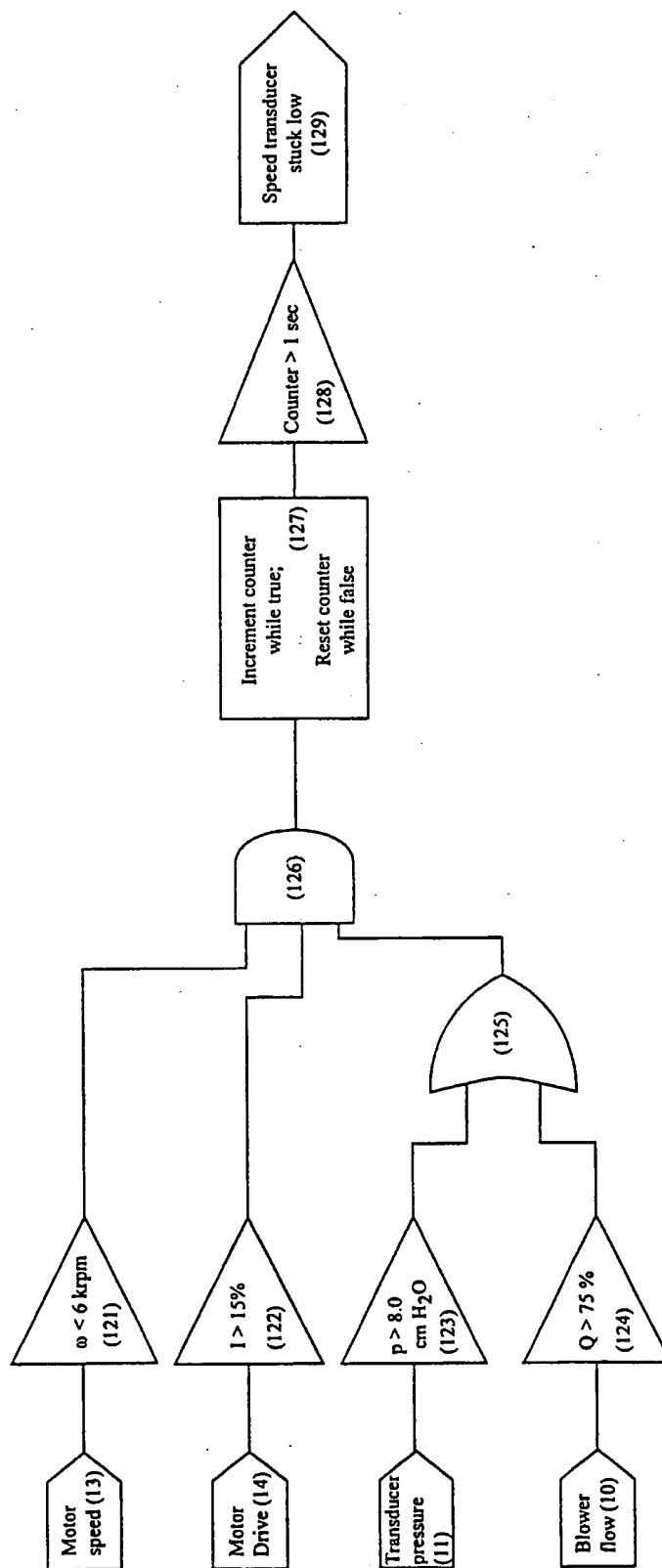


Figure 12: Detect Speed Transducer Stuck Low

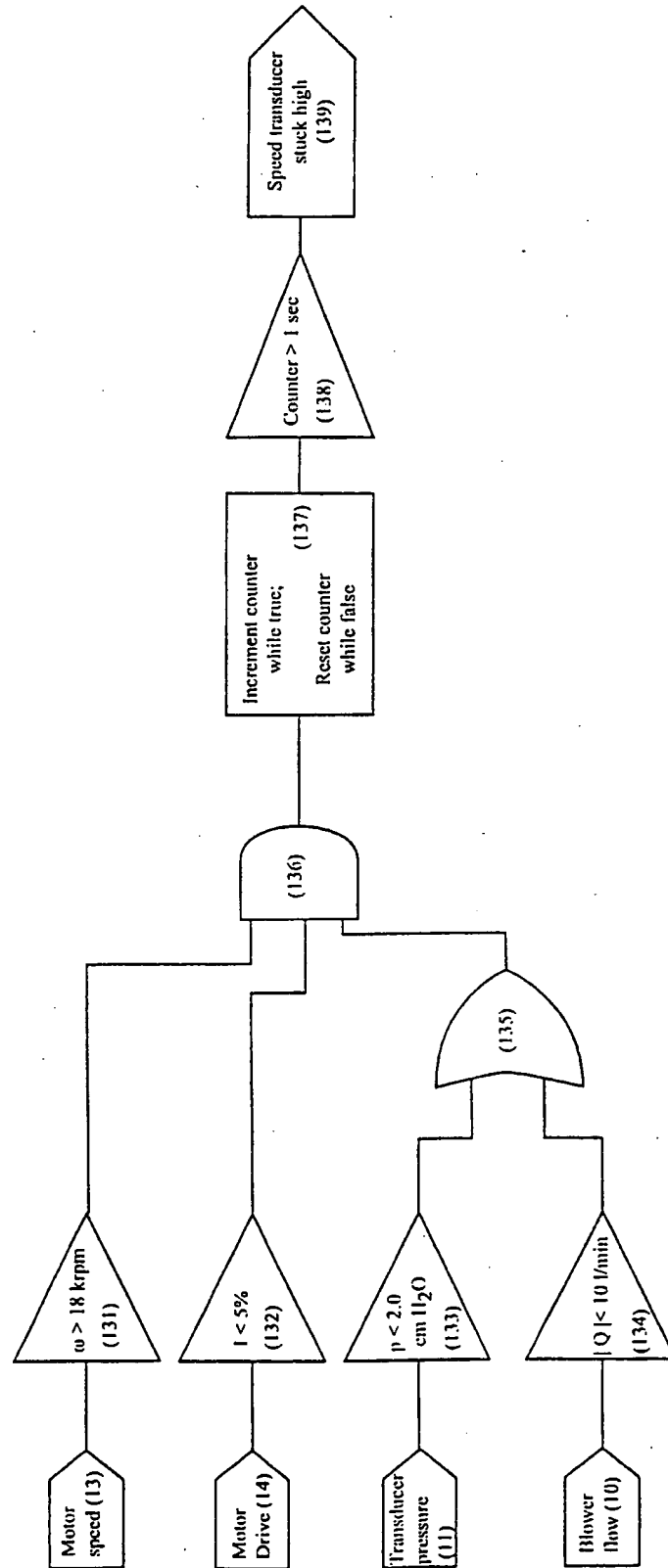
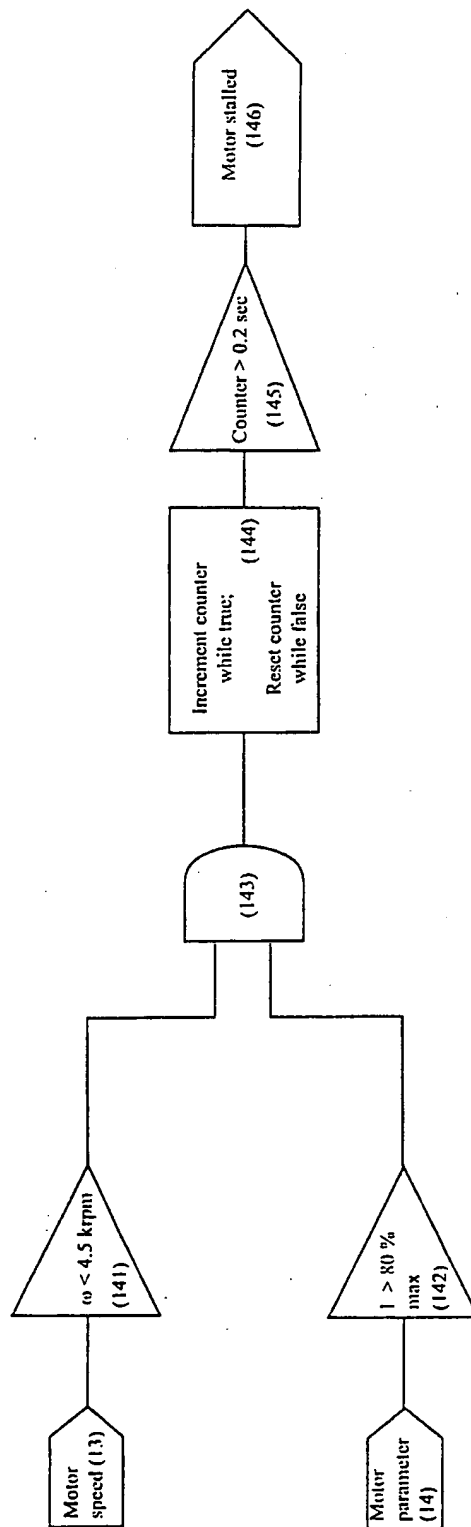
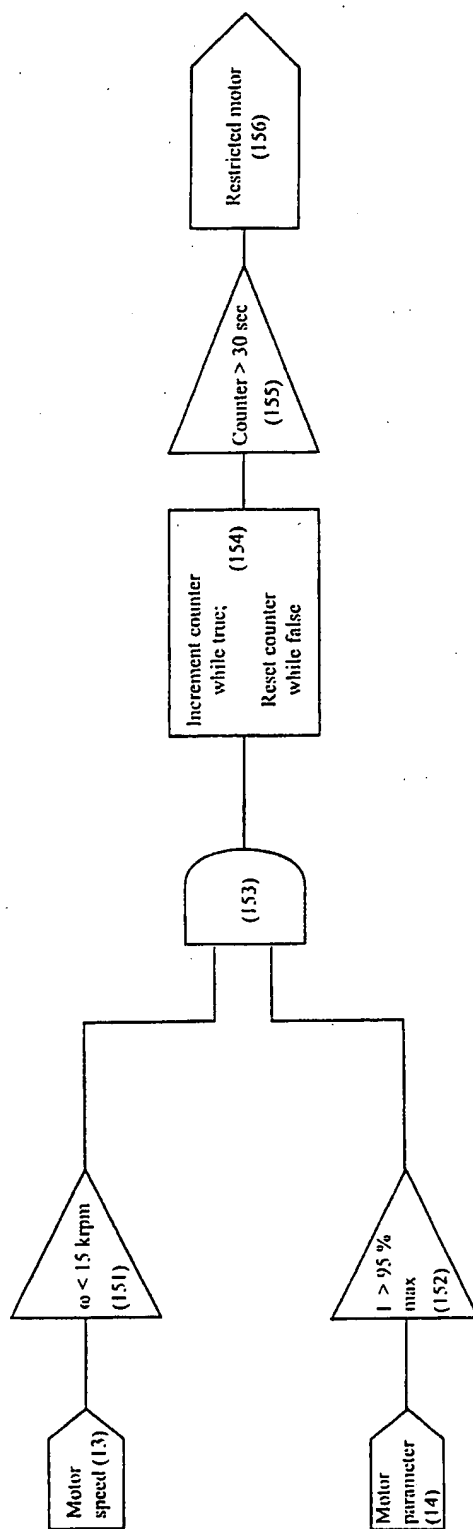


Figure 13: Detect Speed Transducer stuck High

*Figure 14: Detect Stalled Motor*

*Figure 15: Detect Restricted Motor*

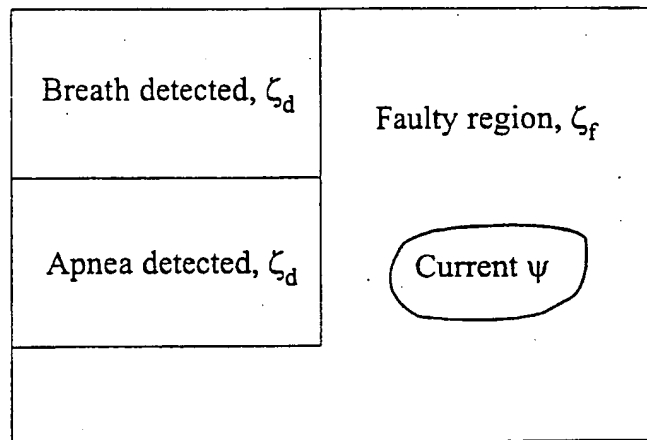


Figure 16: Software fault

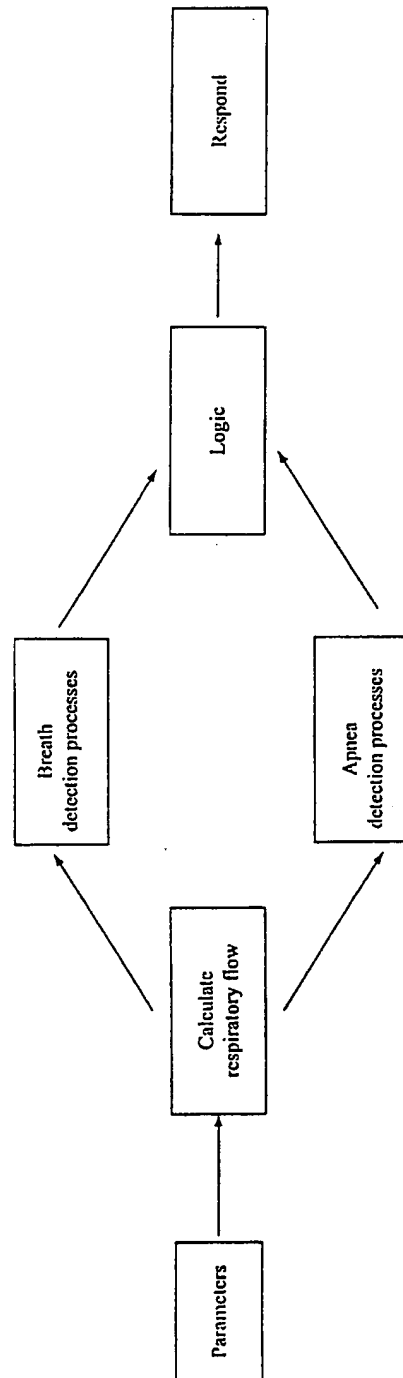



Figure 17: Software fault detection processes

## INTERNATIONAL SEARCH REPORT

International application No.

PCT/AU 99/00972

<b>A. CLASSIFICATION OF SUBJECT MATTER</b>																						
Int Cl <sup>6</sup> : A61M 16/00																						
According to International Patent Classification (IPC) or to both national classification and IPC																						
<b>B. FIELDS SEARCHED</b>																						
Minimum documentation searched (classification system followed by classification symbols)																						
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched																						
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used) WPAT, JAPIO																						
<b>C. DOCUMENTS CONSIDERED TO BE RELEVANT</b>																						
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.																				
X	WO 98/41268 (NELLCOR PURITAN BENNETT INCORPORATED) 24 September 1998 See whole document	1, 3-5																				
X	US 5,662,099 A (TOBIA et al) 2 September 1997 See column 4 lines 22-67	1																				
A	EP 483 556 A (SIEMENS ELEMA AB) 6 May 1992																					
<input checked="" type="checkbox"/> Further documents are listed in the continuation of Box C <input checked="" type="checkbox"/> See patent family annex																						
<p>* Special categories of cited documents:</p> <table border="0"> <tr> <td>"A"</td> <td>Document defining the general state of the art which is not considered to be of particular relevance</td> <td>"T"</td> <td>later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</td> </tr> <tr> <td>"E"</td> <td>earlier application or patent but published on or after the international filing date</td> <td>"X"</td> <td>document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone</td> </tr> <tr> <td>"L"</td> <td>document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</td> <td>"Y"</td> <td>document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art</td> </tr> <tr> <td>"O"</td> <td>document referring to an oral disclosure, use, exhibition or other means</td> <td>"&amp;"</td> <td>document member of the same patent family</td> </tr> <tr> <td>"P"</td> <td>document published prior to the international filing date but later than the priority date claimed</td> <td></td> <td></td> </tr> </table>			"A"	Document defining the general state of the art which is not considered to be of particular relevance	"T"	later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention	"E"	earlier application or patent but published on or after the international filing date	"X"	document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone	"L"	document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"Y"	document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art	"O"	document referring to an oral disclosure, use, exhibition or other means	"&"	document member of the same patent family	"P"	document published prior to the international filing date but later than the priority date claimed		
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"P"	document published prior to the international filing date but later than the priority date claimed																					
Date of the actual completion of the international search 7 January 2000		Date of mailing of the international search report 10 JAN 2000																				
Name and mailing address of the ISA/AU AUSTRALIAN PATENT OFFICE PO BOX 200, WODEN ACT 2606, AUSTRALIA E-mail address: pct@ipaustalia.gov.au Facsimile No. (02) 6285 3929		Authorized officer  <b>BRENDAN BOURKE</b> Telephone No.: (02) 6283 2148																				



# INTERNATIONAL SEARCH REPORT

International application No.

PCT/AU 99/00972

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	GB 2 281 513 A (ULCO ENGINEERING PTY LIMITED) 8 March 1995	
A	EP 621 056 A (MSA (BRITAIN) LTD) 26 October 1994	

## INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.  
**PCT/AU 99/00972**

This Annex lists the known "A" publication level patent family members relating to the patent documents cited in the above-mentioned international search report. The Australian Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent Document Cited in Search Report				Patent Family Member			
WO	98/41268	AU	66689/98	EP	968020	US	5881717
US	5662099	NIL					
EP	621056	AU	59384/94	CA	2121157	US	5577496
EP	483556	JP	4266768	SE	9003466	US	5400777
GB	2281513	AU	71584/94	US	5640149		
							END OF ANNEX